

a)



Jämvikt:

$$\rightarrow: M - M_{v1} = 0 \\ \Rightarrow M_{v1} = M$$

största spänning (3.10)

$$\max(|\tau|) = \frac{M_{v1} \cdot D_1/2}{K_{v1}} = (3.11) = \frac{M_{v1}}{W_{v1}} = \frac{M_{v1}}{\frac{\pi}{2} \left((D_1/2)^3 - \underbrace{\frac{(d_1/2)^4}{D_1/2}}_{(d_1/2)^3} \right)}$$

med $d_1 = 4 D_1/5$, $\max(|\tau|) = \tau_s$, $M_{v1} = M \Rightarrow$ $(d_1/2)^3 \frac{d_1}{D_1}$

$$\tau_s = \frac{M \cdot 2^4}{\pi \cdot D_1^3 \cdot (1 - (4/5)^4)} \Rightarrow D_1 = \left(\frac{M \cdot 2^4}{\pi \cdot (1 - (4/5)^4) \cdot \tau_s} \right)^{1/3}$$

med $\tau_s = 250 \text{ MPa}$, $M = 10^6 \text{ Nmm} \Rightarrow D_1 \approx 32,6 \text{ mm}$

Vridningen blir $\varphi = \frac{M_{v1} \cdot l}{G K_{v1}}$

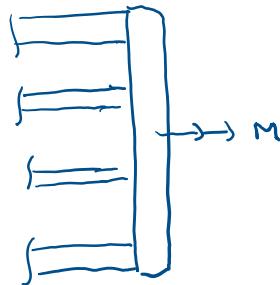
där $l = 1000 \text{ mm}$, $G = \frac{E}{2(1+\nu)} = \frac{200 \cdot 10^3}{2 \cdot 1,3} \approx 77 \cdot 10^3 \text{ MPa}$

$$K_{v1} = \frac{\pi}{2} \left((D_1/2)^4 - \underbrace{(d_1/2)^4}_{D_1/2 \cdot 4/5} \right) \approx 6.51 \cdot 10^4 \text{ mm}^4$$

$$\Rightarrow \varphi = \frac{10^6 \cdot 10^3}{77 \cdot 10^3 \cdot 6.51 \cdot 10^4} \approx 0,2 \text{ rad} \approx 11,4^\circ$$

b)

$$\leftarrow M_{v1} \quad \leftarrow M_{v2}$$



$$\rightarrow: M - M_{v1} - M_{v2} = 0 \quad (*)$$

$$\text{Vridning } \varphi_1 = \frac{M_{v1} \cdot l}{G K_{v1}} \quad \varphi_2 = \frac{M_{v2} \cdot l}{G K_{v2}}$$

$$\text{Deformationsamband } \varphi_1 = \varphi_2 \Rightarrow \frac{M_{v1}}{K_{v1}} = \frac{M_{v2}}{K_{v2}} \quad (**)$$

insatt i $(*) \Rightarrow$

$$M - M_{v1} - M_{v1} \frac{K_{v2}}{K_{v1}} = 0 \Rightarrow M_{v1} = \frac{M \cdot K_{v1}}{K_{v1} + K_{v2}}$$

$$(**) \Rightarrow M_{v2} = \frac{M \cdot K_{v2}}{K_{v1} + K_{v2}}$$

$$K_{v1} = \{ \text{enligt a)} \} \approx 6.51 \cdot 10^4 \text{ mm}^4$$

$$K_{v2} = \pi/2 \left(\underbrace{(D_2/2)^4}_{D_1/4} - \underbrace{(d_2/2)^4}_{d_1/4} \right) \approx 4.07 \cdot 10^3 \text{ mm}^4 = K_{v1}/16$$

$$\text{största skjurspänningar } \tau_{\max,1} = \frac{M_{v1} \cdot D_1/2}{K_{v1}} = \frac{M \cdot D_1/2}{K_{v1} + K_{v2}} \approx 235 \text{ MPa}$$

$$\tau_{\max,2} = \frac{M_{v2} \cdot D_2/2}{K_{v2}} = \frac{M \cdot D_2/2}{K_{v1} + K_{v2}} \approx 118 \text{ MPa}$$

Vridningen

$$\varphi = \varphi_1 = \frac{M_{v1} \cdot l}{G K_{v1}} = \frac{M_{v2} \cdot l}{G K_{v2}} \approx \frac{M \cdot l}{G (K_{v1} + K_{v2})} \approx 0,188 \text{ rad} \\ \approx 10,8^\circ //$$

a) Enl (6.5)

$$\begin{bmatrix} \sigma_x \\ \sigma_y \\ \sigma_z \\ \tau_{xy} \\ \tau_{xz} \\ \tau_{yz} \end{bmatrix} = \frac{\bar{E}}{(1+\nu)(1-2\nu)} \begin{bmatrix} 1-\nu & \nu & \nu & 0 & 0 & 0 \\ \nu & 1-\nu & \nu & 0 & 0 & 0 \\ \nu & \nu & 1-\nu & 0 & 0 & 0 \\ 0 & 0 & 0 & \frac{1-2\nu}{2} & 0 & 0 \\ 0 & 0 & 0 & 0 & \frac{1-2\nu}{2} & 0 \\ 0 & 0 & 0 & 0 & 0 & \frac{1-2\nu}{2} \end{bmatrix} \begin{bmatrix} \varepsilon_x \\ \varepsilon_y \\ \varepsilon_z \\ \gamma_{xy} \\ \gamma_{xz} \\ \gamma_{yz} \end{bmatrix}$$

med $\bar{E} = 200 \cdot 10^3$ MPa, $\nu = 0,3$

$$\varepsilon_x = 0,002, \quad \varepsilon_y = -0,001, \quad \varepsilon_z = 0,001$$

$$\gamma_{xy} = 0,005, \quad \gamma_{yz} = \gamma_{xz} = 0$$

fås $\sigma_x \approx 538$ MPa, $\sigma_y \approx 76,9$ MPa, $\sigma_z \approx 385$ MPa

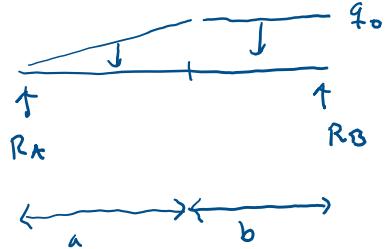
$$\tau_{xy} \approx 385 \text{ MPa}, \quad \tau_{xz} = \tau_{yz} = 0 \quad //$$

b) Med $S = \begin{bmatrix} \sigma_x & \tau_{xy} & \tau_{xz} \\ \tau_{xy} & \sigma_y & \tau_{yz} \\ \tau_{xz} & \tau_{yz} & \sigma_z \end{bmatrix}$ och Matlabkod 4.7.1
resp 4.7.2

fås $\sigma_e^{VM} \approx 781$ MPa

$$\sigma_e^T \approx 897 \text{ MPa} \quad //$$

Stödreaktioner



$$\uparrow: R_A + R_B - q_0 \cdot a/2 - q_0 \cdot b = 0$$

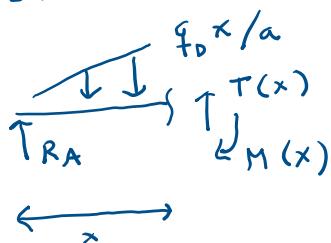
$$\cancel{\text{Av}}: -R_B \cdot (a+b) + q_0 \cdot a/2 \cdot 2a/3 + q_0 \cdot b \cdot (a+b/2) = 0$$

$$\Rightarrow \begin{cases} R_B = \frac{q_0 [a^2/3 + b(a+b/2)]}{a+b} \\ R_A = q_0 [a/2 + b] - R_B \end{cases}$$

$$\Rightarrow R_A \approx 722 \text{ N}, R_B \approx 1,28 \text{ kN}$$

Snitta

$$0 \leq x \leq a$$



$$\uparrow: R_A - (q_0 \cdot x/a) \frac{1}{2} \cdot x + T(x) = 0$$

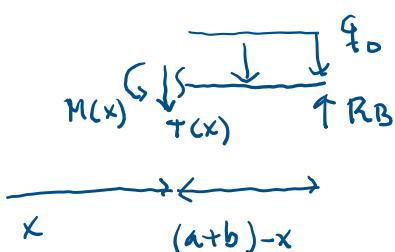
$$\Rightarrow T(x) = q_0 \cdot x^2 / (2a) - R_A$$

$$\cancel{\text{Av}}: R_A \cdot x - (q_0 \cdot x/a) \frac{1}{2} x \cdot \frac{1}{3} x + M(x) = 0$$

$$\Rightarrow M(x) = q_0 \cdot x^3 / (6a) - R_A \cdot x$$

$$\cancel{\text{Av}}: T(x) = M'(x) = 0 \quad d\overset{\circ}{x} / dx = \sqrt{\frac{R_A \cdot 2a}{q_0}}$$

$$a \leq x \leq (a+b)$$



$$\uparrow: R_B - q_0 (a+b-x) - T(x) = 0$$

$$\Rightarrow T(x) = R_B - q_0 (a+b-x)$$

$$\cancel{\text{Av}}: -R_B (a+b-x) + q_0 (a+b-x) \frac{a+b-x}{2} - M(x) = 0$$

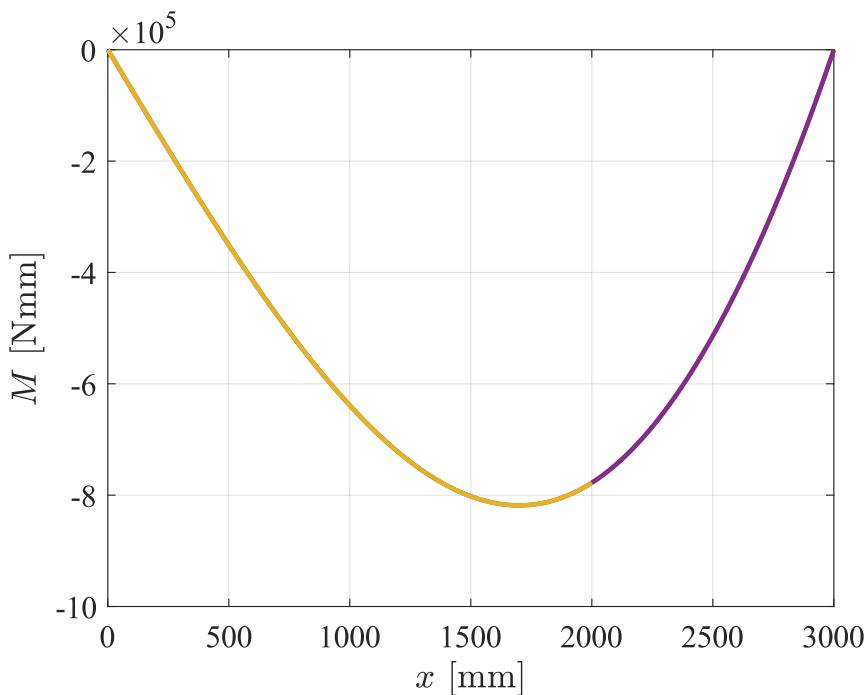
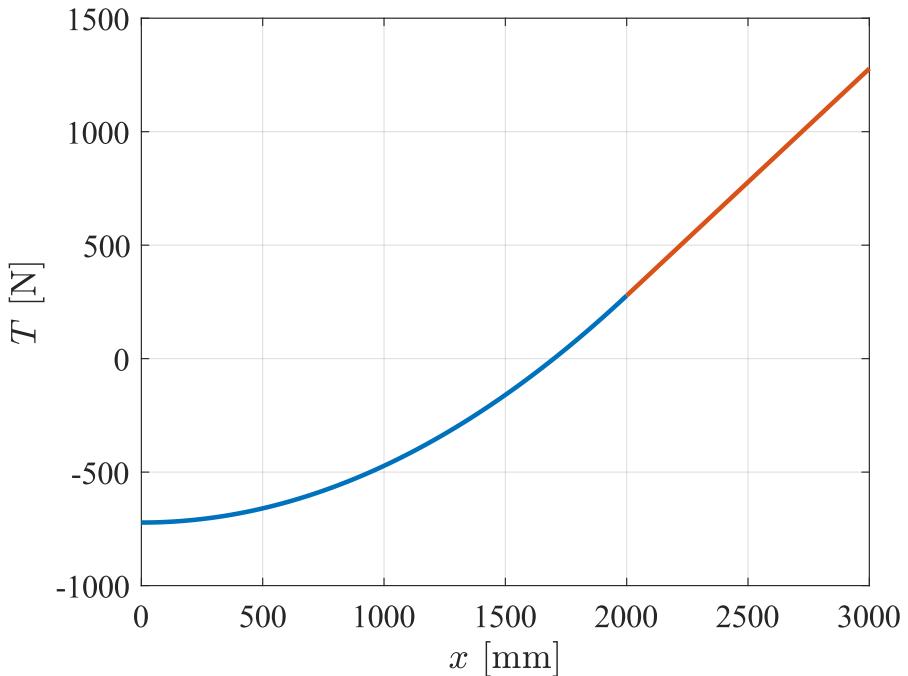
$$\Rightarrow M(x) = R_B (x-a-b) + q_0 (a+b-x)^2 / 2$$

```

x=linspace(0,a,100);
T1=q0*x.^2/(2*a)-RA; M1=q0*x.^3/(6*a)-RA*x;
figure(1)
plot(x,T1,'linewidth',2)
set(gca,'FontSize',14,'fontname','Times New Roman')
xlabel('x [mm]', 'FontSize',16,'interpreter','latex')
ylabel('T [N]', 'FontSize',16,'interpreter','latex')
hold on
x=linspace(a,a+b,100);
T2=RB-q0*(a+b-x); M2=RB*(x-a-b)+q0*(a+b-x).^2/2;
plot(x,T2,'linewidth',2)

x=linspace(0,a,100);
figure(2)
plot(x,M1,'linewidth',2)
set(gca,'FontSize',14,'fontname','Times New Roman')
xlabel('x [mm]', 'FontSize',16,'interpreter','latex')
ylabel('M [Nm]', 'FontSize',16,'interpreter','latex')
hold on
x=linspace(a,a+b,100);
plot(x,M2,'linewidth',2)
g

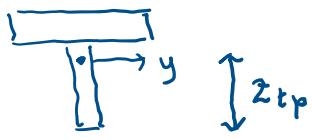
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Största
 (till belopp)
 böjmoment

$$x = \sqrt{\frac{R_A \cdot 2a}{q_0}}$$

 $\approx 1700 \text{ mm}$
 $\Rightarrow |M|_{\max} \approx$
 $8,18 \cdot 10^5 \text{ Nmm}$



Ytcentrum

$$z_{tp} = \frac{b_1 h_1 \cdot h_1 / 2 + b_2 h_2 \cdot (h_1 + h_2 / 2)}{b_1 h_1 + b_2 h_2} =$$

$$\approx 38,75 \text{ mm}$$

Yttroghetsmomentet (Steiners sats)

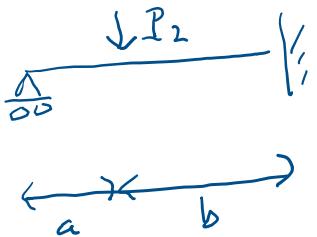
$$I_y = \frac{b_1 h_1^3}{12} + b_1 h_1 (z_{tp} - h_1 / 2)^2 + \\ + \frac{b_2 h_2^3}{12} + b_2 h_2 (h_1 + h_2 / 2 - z_{tp})^2 \approx 1,471 \cdot 10^5 \text{ mm}^4$$

Största normalspanningen

$$|\sigma|_{\max} = \frac{|M|_{\max} \cdot z_{tp}}{I_y} \approx 216 \text{ MPa} //$$

Enl FS 6.5 fås

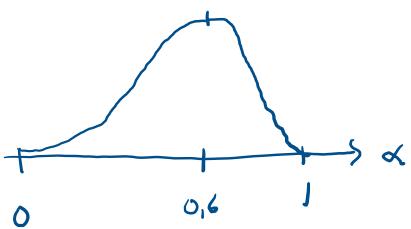
$$P_2 = \frac{P_2 a^2 b^3}{12 EI L^2} \left[4 - \frac{b}{L} \right]$$



eftersom spegelvänd $b = \alpha L$, $a = (1-\alpha)L \Rightarrow$ utböjning vid lasten

$$P = \frac{P (1-\alpha)^2 \alpha^3 \cdot L^3}{12 \cdot EI} \left[4 - \alpha \right] = \frac{P L^3}{12 EI} \underbrace{(1-\alpha)^2 \alpha^3 (4-\alpha)}_{f(\alpha)}$$

plotta $f(\alpha)$ i Matlab



maxvärde
fås enligt

Matlabgraf vid $\alpha \approx 0.59$

Alternativ:

kolla ändpunkter

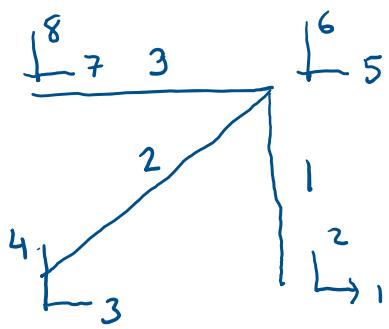
$$f(0) = 0, \quad f(1) = 0$$

$$\begin{aligned} f'(\alpha) &= -2(1-\alpha)\alpha^3(4-\alpha) + (1-\alpha)^2 3\alpha^2(4-\alpha) - (1-\alpha)^2 \alpha^3 = \\ &= (1-\alpha)\alpha^2 \left[-2\alpha(4-\alpha) + (1-\alpha)3(4-\alpha) - (1-\alpha)\alpha \right] = 0 \end{aligned}$$

$$\Rightarrow -8\alpha + 2\alpha^2 + 3 \cdot (4 - 5\alpha + \alpha^2) - \alpha + \alpha^2 = 0 \Rightarrow$$

$$\Rightarrow 6\alpha^2 - 24\alpha + 12 = 0 \Rightarrow \alpha^2 - 4\alpha + 2 = 0 \Rightarrow$$

$$\alpha = 2 \pm \sqrt{4 - 2} = 2 \pm \sqrt{2} \quad \text{men } 0 \leq \alpha \leq 1 \Rightarrow \alpha = 2 - \sqrt{2} \approx 0.59 //$$



element och frihetsgrader

Se Matlabkod nedan

utan element 3 får $u_5 \approx 0,67 \text{ mm}$

$$u_6 \approx -0,087 \text{ mm}$$

Med element 3 får $u_5 \approx 0,14 \text{ mm}$

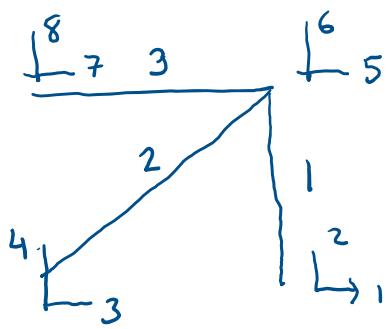
$$u_6 \approx 0,05 \text{ mm}$$

Inre normalkrafter

utan element 3 : $\begin{cases} N_1 \approx -3,66 \text{ kN} \\ N_2 \approx 12,2 \text{ kN} \end{cases}$

Förslag 2 $P_{kr} = \frac{\pi^2 EI}{L^2}$

\Rightarrow "säkerhetsfaktor $\approx 1,8$ //



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Inre normalkrafter

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Euler 2 $P_{kr} = \frac{\pi^2 EI}{L^2}$

\Rightarrow "säkerhetsfaktor $\approx 1,8$ //

```

clear all
syms a1 a2 a3 a4 a5 a6 P1 P2 P3 P4 P5 P6
%givna storheter
P=10e3;
Em=210e3; A=100;
EA=Em*A; L=500;
%givet
a1=0; a2=0; a3=0; a4=0;
P5=P*cos(pi/6); P6=P*sin(pi/6);
%definiera avektor pvektor
avektor = [a1; a2; a3; a4; a5; a6];
Pvektor = [P1; P2; P3; P4; P5; P6];
%elementstyper
%%%Element 1:
L1=L; EA1=EA; alpha1=pi/2; c=cos(alpha1);s=sin(alpha1);
Ke1=EA1/L1*[ c^2 c*s -c^2 -c*s;
c*s s^2 -c*s -s^2;
-c^2 -c*s c^2 c*s;
-c*s -s^2 c*s s^2];
Kmatris1=sym(zeros(6,6));
Kmatris1([1 2 5 6],[1 2 5 6]) = Ke1;
%%%Element 2:
L2=L*sqrt(2); EA2=EA; alpha2=pi/4; c=cos(alpha2);s=sin(alpha2);
Ke2=EA2/L2*[ c^2 c*s -c^2 -c*s;
c*s s^2 -c*s -s^2;
-c^2 -c*s c^2 c*s;
-c*s -s^2 c*s s^2];
Kmatris2=sym(zeros(6,6));
Kmatris2([3 4 5 6],[3 4 5 6]) = Ke2;
%addera
Ktot=Kmatris1+Kmatris2;
%Lös de obekanta
Sol = solve(double(Ktot)*avektor==Pvektor,[a5,a6,P1,P2,P3,P4])
%Skriv ut resultat
double(Sol.a5)
double(Sol.a6)
double(Sol.P1)
double(Sol.P2)
double(Sol.P3)
double(Sol.P4)
%förlängningarna av stängerna enl s.208
ubar1=[cos(alpha1) sin(alpha1) 0 0; 0 0 cos(alpha1) sin(alpha1)]*[a1; a2; Sol.a5; Sol.a6]
delta1=ubar1(2)-ubar1(1);
eps1=delta1/L1;
N1=double(Em*eps1*A)
ubar2=[cos(alpha2) sin(alpha2) 0 0; 0 0 cos(alpha2) sin(alpha2)]*[a3; a4; Sol.a5; Sol.a6]
delta2=ubar2(2)-ubar2(1);
eps2=delta2/L2;
N2=double(Em*eps2*A)
%beräkning av d: pi d^2/4=A och sedan av yttröghetsmoment (enl FS)
d=sqrt( A^4/pi); ly=pi*(d/2)^4/4;
%Knäckning enligt Euler 2 av stång 1:
Pkr=pi^2*Em*ly/L1^2
%säkerhetsfaktor mot knäckning
Pkr/(-N1)

```

```

clear all
syms a1 a2 a3 a4 a5 a6 a7 a8 P1 P2 P3 P4 P5 P6 P7 P8
%givna storheter
P=10e3;
Em=210e3;
EA=Em*100; L=500;
a1=0; a2=0; a3=0; a4=0; a7=0; a8=0;
P5=P*cos(pi/6); P6=P*sin(pi/6);
%definiera avektor pvektor
avektor = [a1; a2; a3; a4; a5; a6; a7; a8];
Pvektor = [P1; P2; P3; P4; P5; P6; P7; P8];
%elementstyper
%%%Element 1:
L1=L; EA1=EA; alpha1=pi/2; c=cos(alpha1);s=sin(alpha1);
Ke1=EA1/L1*[ c^2 c*s -c^2 -c*s;
c*s s^2 -c*s -s^2;
-c^2 -c*s c^2 c*s;
-c*s -s^2 c*s s^2];
Kmatris1=sym(zeros(8,8));
Kmatris1([1 2 5 6],[1 2 5 6]) = Ke1;
%%%Element 2:
L2=L*sqrt(2); EA2=EA; alpha2=pi/4; c=cos(alpha2);s=sin(alpha2);
Ke2=EA2/L2*[ c^2 c*s -c^2 -c*s;
c*s s^2 -c*s -s^2;
-c^2 -c*s c^2 c*s;
-c*s -s^2 c*s s^2];
Kmatris2=sym(zeros(8,8));
Kmatris2([3 4 5 6],[3 4 5 6]) = Ke2;
%%%Element 3:
L3=L; EA3=EA; alpha3=0; c=cos(alpha3);s=sin(alpha3);
Ke3=EA3/L3*[ c^2 c*s -c^2 -c*s;
c*s s^2 -c*s -s^2;
-c^2 -c*s c^2 c*s;
-c*s -s^2 c*s s^2];
Kmatris3=sym(zeros(8,8));
Kmatris3([7 8 5 6],[7 8 5 6]) = Ke3;
%addera
Ktot=Kmatris1+Kmatris2+Kmatris3;
%Lös de obekanta
Sol = solve(double(Ktot)*avektor==Pvektor,[a5,a6,P1,P2,P3, P4, P7,P8])
%Skriv ut resultat
double(Sol.a5)
double(Sol.a6)
double(Sol.P1)
double(Sol.P2)
double(Sol.P3)
double(Sol.P4)
double(Sol.P7)
double(Sol.P8)

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a)



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$$\rightarrow: M - M_{v1} = 0 \\ \Rightarrow M_{v1} = M$$

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$$\max(|\tau|) = \frac{M_{v1} \cdot D_1/2}{K_{v1}} = (3.11) = \frac{M_{v1}}{W_{v1}} = \frac{M_{v1}}{\frac{\pi}{2} \left((D_1/2)^3 - \underbrace{\frac{(d_1/2)^4}{D_1/2}}_{(d_1/2)^3} \right)}$$

med $d_1 = 4 D_1/5$, $\max(|\tau|) = \tau_s$, $M_{v1} = M \Rightarrow$ $(d_1/2)^3 \frac{d_1}{D_1}$

$$\tau_s = \frac{M \cdot 2^4}{\pi \cdot D_1^3 \cdot (1 - (4/5)^4)} \Rightarrow D_1 = \left(\frac{M \cdot 2^4}{\pi \cdot (1 - (4/5)^4) \cdot \tau_s} \right)^{1/3}$$

med $\tau_s = 250 \text{ MPa}$, $M = 10^6 \text{ Nmm} \Rightarrow D_1 \approx 32,6 \text{ mm}$

Vridningen blir $\varphi = \frac{M_{v1} \cdot l}{G K_{v1}}$

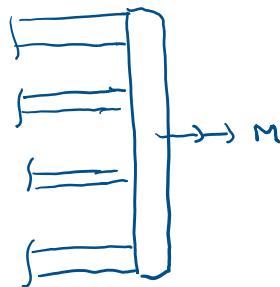
där $l = 1000 \text{ mm}$, $G = \frac{E}{2(1+\nu)} = \frac{200 \cdot 10^3}{2 \cdot 1,3} \approx 77 \cdot 10^3 \text{ MPa}$

$$K_{v1} = \frac{\pi}{2} \left((D_1/2)^4 - \underbrace{(d_1/2)^4}_{D_1/2 \cdot 4/5} \right) \approx 6.51 \cdot 10^4 \text{ mm}^4$$

$$\Rightarrow \varphi = \frac{10^6 \cdot 10^3}{77 \cdot 10^3 \cdot 6.51 \cdot 10^4} \approx 0,2 \text{ rad} \approx 11,4^\circ$$

b)

$$\leftarrow \begin{array}{l} M_{v1} \\ M_{v2} \end{array}$$



$$\rightarrow: M - M_{v1} - M_{v2} = 0 \quad (*)$$

$$\text{Vridning } \varphi_1 = \frac{M_{v1} \cdot l}{G K_{v1}} \quad \varphi_2 = \frac{M_{v2} \cdot l}{G K_{v2}}$$

$$\text{Deformationsamband } \varphi_1 = \varphi_2 \Rightarrow \frac{M_{v1}}{K_{v1}} = \frac{M_{v2}}{K_{v2}} \quad (**)$$

insatt i $(*) \Rightarrow$

$$M - M_{v1} - M_{v1} \frac{K_{v2}}{K_{v1}} = 0 \Leftrightarrow M_{v1} = \frac{M \cdot K_{v1}}{K_{v1} + K_{v2}}$$

$$(**) \Rightarrow M_{v2} = \frac{M \cdot K_{v2}}{K_{v1} + K_{v2}}$$

$$K_{v1} = \{ \text{enligt a)} \} \approx 6.51 \cdot 10^4 \text{ mm}^4$$

$$K_{v2} = \pi/2 \left(\underbrace{(D_2/2)^4}_{D_1/4} - \underbrace{(d_2/2)^4}_{d_1/4} \right) \approx 4.07 \cdot 10^3 \text{ mm}^4 = K_{v1}/16$$

$$\text{största skjurspänningar } \tau_{\max,1} = \frac{M_{v1} \cdot D_1/2}{K_{v1}} = \frac{M \cdot D_1/2}{K_{v1} + K_{v2}} \approx 235 \text{ MPa}$$

$$\tau_{\max,2} = \frac{M_{v2} \cdot D_2/2}{K_{v2}} = \frac{M \cdot D_2/2}{K_{v1} + K_{v2}} \approx 118 \text{ MPa}$$

Vridningen

$$\varphi = \varphi_1 = \frac{M_{v1} \cdot l}{G K_{v1}} = \frac{M_{v2} \cdot l}{G K_{v2}} \approx \frac{M \cdot l}{G (K_{v1} + K_{v2})} \approx 0,188 \text{ rad} \approx 10,8^\circ //$$

a) Enl (6.5)

$$\begin{bmatrix} \sigma_x \\ \sigma_y \\ \sigma_z \\ \tau_{xy} \\ \tau_{xz} \\ \tau_{yz} \end{bmatrix} = \frac{\bar{E}}{(1+\nu)(1-2\nu)} \begin{bmatrix} 1-\nu & \nu & \nu & 0 & 0 & 0 \\ \nu & 1-\nu & \nu & 0 & 0 & 0 \\ \nu & \nu & 1-\nu & 0 & 0 & 0 \\ 0 & 0 & 0 & \frac{1-2\nu}{2} & 0 & 0 \\ 0 & 0 & 0 & 0 & \frac{1-2\nu}{2} & 0 \\ 0 & 0 & 0 & 0 & 0 & \frac{1-2\nu}{2} \end{bmatrix} \begin{bmatrix} \varepsilon_x \\ \varepsilon_y \\ \varepsilon_z \\ \gamma_{xy} \\ \gamma_{xz} \\ \gamma_{yz} \end{bmatrix}$$

med $\bar{E} = 200 \cdot 10^3$ MPa, $\nu = 0,3$

$$\varepsilon_x = 0,002, \quad \varepsilon_y = -0,001, \quad \varepsilon_z = 0,001$$

$$\gamma_{xy} = 0,005, \quad \gamma_{yz} = \gamma_{xz} = 0$$

fås $\sigma_x \approx 538$ MPa, $\sigma_y \approx 76,9$ MPa, $\sigma_z \approx 385$ MPa

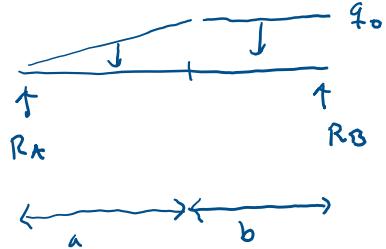
$$\tau_{xy} \approx 385 \text{ MPa}, \quad \tau_{xz} = \tau_{yz} = 0 \quad //$$

b) Med $S = \begin{bmatrix} \sigma_x & \tau_{xy} & \tau_{xz} \\ \tau_{xy} & \sigma_y & \tau_{yz} \\ \tau_{xz} & \tau_{yz} & \sigma_z \end{bmatrix}$ och Matlabkod 4.7.1
resp 4.7.2

fås $\sigma_e^{VM} \approx 781$ MPa

$$\sigma_e^T \approx 897 \text{ MPa} \quad //$$

Stödreaktioner



$$\uparrow: R_A + R_B - q_0 \cdot a/2 - q_0 \cdot b = 0$$

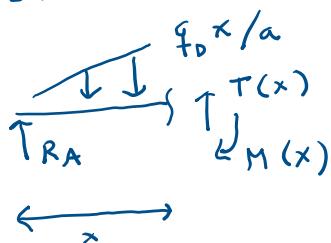
$$\cancel{\text{Av}}: -R_B \cdot (a+b) + q_0 \cdot a/2 \cdot 2a/3 + q_0 \cdot b \cdot (a+b/2) = 0$$

$$\Rightarrow \begin{cases} R_B = \frac{q_0 [a^2/3 + b(a+b/2)]}{a+b} \\ R_A = q_0 [a/2 + b] - R_B \end{cases}$$

$$\Rightarrow R_A \approx 722 \text{ N}, R_B \approx 1,28 \text{ kN}$$

Snitta

$$0 \leq x \leq a$$



$$\uparrow: R_A - (q_0 \cdot x/a) \frac{1}{2} \cdot x + T(x) = 0$$

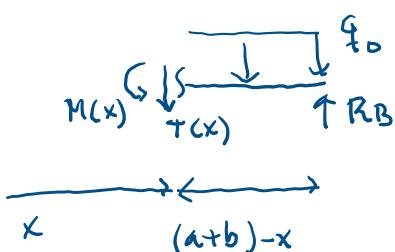
$$\Rightarrow T(x) = q_0 \cdot x^2 / (2a) - R_A$$

$$\cancel{\text{Av}}: R_A \cdot x - (q_0 \cdot x/a) \frac{1}{2} x \cdot \frac{1}{3} x + M(x) = 0$$

$$\Rightarrow M(x) = q_0 \cdot x^3 / (6a) - R_A \cdot x$$

$$\cancel{\text{Av}}: T(x) = M'(x) = 0 \quad d\overset{\circ}{x} / dx = \sqrt{\frac{R_A \cdot 2a}{q_0}}$$

$$a \leq x \leq (a+b)$$



$$\uparrow: R_B - q_0 (a+b-x) - T(x) = 0$$

$$\Rightarrow T(x) = R_B - q_0 (a+b-x)$$

$$\cancel{\text{Av}}: -R_B (a+b-x) + q_0 (a+b-x) \frac{a+b-x}{2} - M(x) = 0$$

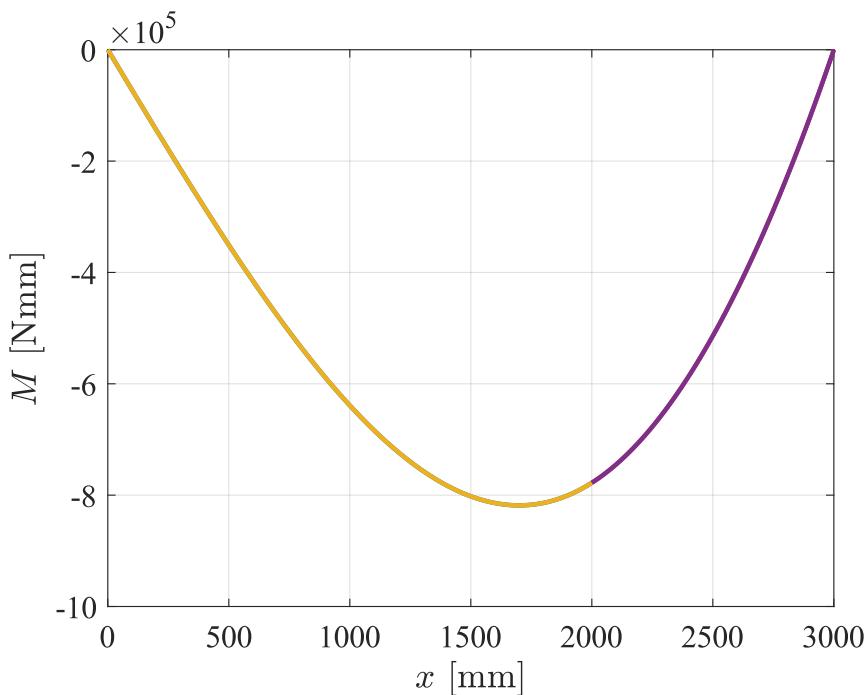
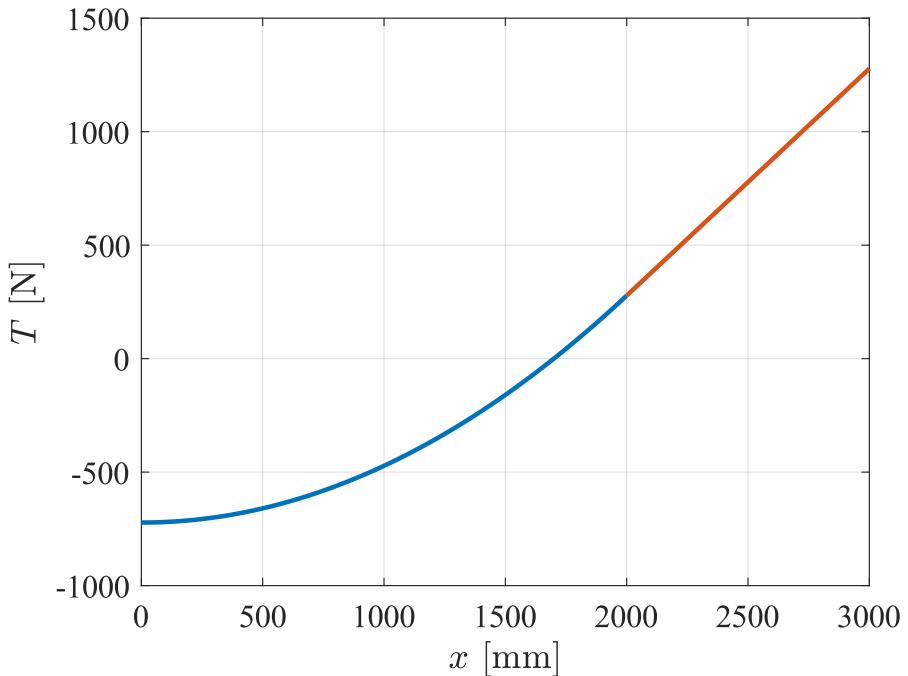
$$\Rightarrow M(x) = R_B (x-a-b) + q_0 (a+b-x)^2 / 2$$

```

x=linspace(0,a,100);
T1=q0*x.^2/(2*a)-RA; M1=q0*x.^3/(6*a)-RA*x;
figure(1)
plot(x,T1,'linewidth',2)
set(gca,'FontSize',14,'fontname','Times New Roman')
xlabel('x [mm]', 'FontSize',16,'interpreter','latex')
ylabel('T [N]', 'FontSize',16,'interpreter','latex')
hold on
x=linspace(a,a+b,100);
T2=RB-q0*(a+b-x); M2=RB*(x-a-b)+q0*(a+b-x).^2/2;
plot(x,T2,'linewidth',2)

x=linspace(0,a,100);
figure(2)
plot(x,M1,'linewidth',2)
set(gca,'FontSize',14,'fontname','Times New Roman')
xlabel('x [mm]', 'FontSize',16,'interpreter','latex')
ylabel('M [Nm]', 'FontSize',16,'interpreter','latex')
hold on
x=linspace(a,a+b,100);
plot(x,M2,'linewidth',2)
g

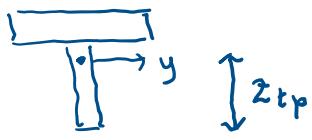
```



Största
 (till belopp)
 böjmoment

$$x = \sqrt{\frac{R_A \cdot 2a}{q_0}}$$

 $\approx 1700 \text{ mm}$
 $\Rightarrow |M|_{\max} \approx$
 $8,18 \cdot 10^5 \text{ Nmm}$



Ytcentrum

$$z_{tp} = \frac{b_1 h_1 \cdot h_1 / 2 + b_2 h_2 \cdot (h_1 + h_2 / 2)}{b_1 h_1 + b_2 h_2} =$$

$$\approx 38,75 \text{ mm}$$

Yttroghetsmomentet (Steiners sats)

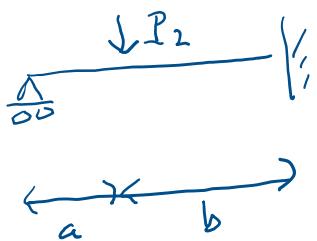
$$I_y = \frac{b_1 h_1^3}{12} + b_1 h_1 (z_{tp} - h_1 / 2)^2 + \\ + \frac{b_2 h_2^3}{12} + b_2 h_2 (h_1 + h_2 / 2 - z_{tp})^2 \approx 1,471 \cdot 10^5 \text{ mm}^4$$

Största normalspanningen

$$|\sigma|_{\max} = \frac{|M|_{\max} \cdot z_{tp}}{I_y} \approx 216 \text{ MPa} //$$

Enl FS 6.5 fås

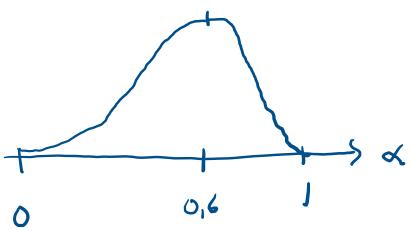
$$P_2 = \frac{P_2 a^2 b^3}{12 EI L^2} \left[4 - \frac{b}{L} \right]$$



eftersom spegelvänd $b = \alpha L$, $a = (1-\alpha)L \Rightarrow$ utböjning vid lasten

$$P = \frac{P (1-\alpha)^2 \alpha^3 \cdot L^3}{12 \cdot EI} \left[4 - \alpha \right] = \frac{P L^3}{12 EI} \underbrace{(1-\alpha)^2 \alpha^3 (4-\alpha)}_{f(\alpha)}$$

plotta $f(\alpha)$ i Matlab



maxvärde

fås enligt

Matlabgraf vid $\alpha \approx 0.59$

Alternativ:

kolla ändpunkter

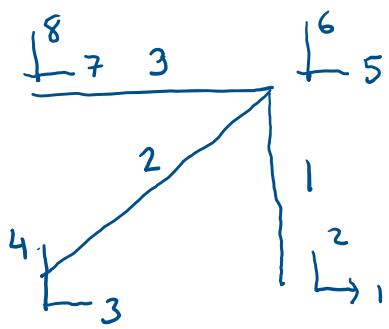
$$f(0) = 0, \quad f(1) = 0$$

$$\begin{aligned} f'(\alpha) &= -2(1-\alpha)\alpha^3(4-\alpha) + (1-\alpha)^2 3\alpha^2(4-\alpha) - (1-\alpha)^2 \alpha^3 = \\ &= (1-\alpha)\alpha^2 \left[-2\alpha(4-\alpha) + (1-\alpha)3(4-\alpha) - (1-\alpha)\alpha \right] = 0 \end{aligned}$$

$$\Rightarrow -8\alpha + 2\alpha^2 + 3 \cdot (4 - 5\alpha + \alpha^2) - \alpha + \alpha^2 = 0 \Rightarrow$$

$$\Rightarrow 6\alpha^2 - 24\alpha + 12 = 0 \Rightarrow \alpha^2 - 4\alpha + 2 = 0 \Rightarrow$$

$$\alpha = 2 \pm \sqrt{4 - 2} = 2 \pm \sqrt{2} \quad \text{men } 0 \leq \alpha \leq 1 \Rightarrow \alpha = 2 - \sqrt{2} \approx 0.59 //$$



element och frihetsgrader

Se Matlabkod nedan

utan element 3 får $u_5 \approx 0,67 \text{ mm}$

$$u_6 \approx -0,087 \text{ mm}$$

Med element 3 får $u_5 \approx 0,14 \text{ mm}$

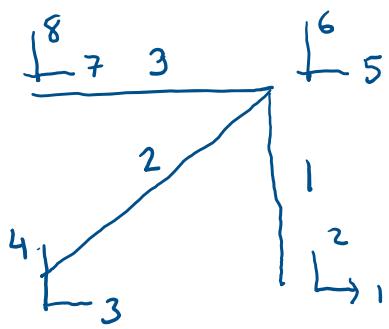
$$u_6 \approx 0,05 \text{ mm}$$

Inre normalkrafter

utan element 3 : $\begin{cases} N_1 \approx -3,66 \text{ kN} \\ N_2 \approx 12,2 \text{ kN} \end{cases}$

Förslag 2 $P_{kr} = \frac{\pi^2 EI}{l^2}$

\Rightarrow "säkerhetsfaktor $\approx 1,8$ //



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Förslag 2 $P_{kr} = \frac{\pi^2 EI}{l^2}$

\Rightarrow "säkerhetsfaktor $\approx 1,8$ //

```

clear all
syms a1 a2 a3 a4 a5 a6 P1 P2 P3 P4 P5 P6
%givna storheter
P=10e3;
Em=210e3; A=100;
EA=Em*A; L=500;
%givet
a1=0; a2=0; a3=0; a4=0;
P5=P*cos(pi/6); P6=P*sin(pi/6);
%definiera avektor pvektor
avektor = [a1; a2; a3; a4; a5; a6];
Pvektor = [P1; P2; P3; P4; P5; P6];
%elementstyper
%%%Element 1:
L1=L; EA1=EA; alpha1=pi/2; c=cos(alpha1);s=sin(alpha1);
Ke1=EA1/L1*[ c^2 c*s -c^2 -c*s;
c*s s^2 -c*s -s^2;
-c^2 -c*s c^2 c*s;
-c*s -s^2 c*s s^2];
Kmatris1=sym(zeros(6,6));
Kmatris1([1 2 5 6],[1 2 5 6]) = Ke1;
%%%Element 2:
L2=L*sqrt(2); EA2=EA; alpha2=pi/4; c=cos(alpha2);s=sin(alpha2);
Ke2=EA2/L2*[ c^2 c*s -c^2 -c*s;
c*s s^2 -c*s -s^2;
-c^2 -c*s c^2 c*s;
-c*s -s^2 c*s s^2];
Kmatris2=sym(zeros(6,6));
Kmatris2([3 4 5 6],[3 4 5 6]) = Ke2;
%addera
Ktot=Kmatris1+Kmatris2;
%Lös de obekanta
Sol = solve(double(Ktot)*avektor==Pvektor,[a5,a6,P1,P2,P3,P4])
%Skriv ut resultat
double(Sol.a5)
double(Sol.a6)
double(Sol.P1)
double(Sol.P2)
double(Sol.P3)
double(Sol.P4)
%förlängningarna av stängerna enl s.208
ubar1=[cos(alpha1) sin(alpha1) 0 0; 0 0 cos(alpha1) sin(alpha1)]*[a1; a2; Sol.a5; Sol.a6]
delta1=ubar1(2)-ubar1(1);
eps1=delta1/L1;
N1=double(Em*eps1*A)
ubar2=[cos(alpha2) sin(alpha2) 0 0; 0 0 cos(alpha2) sin(alpha2)]*[a3; a4; Sol.a5; Sol.a6]
delta2=ubar2(2)-ubar2(1);
eps2=delta2/L2;
N2=double(Em*eps2*A)
%beräkning av d: pi d^2/4=A och sedan av yttröghetsmoment (enl FS)
d=sqrt(A^4/pi); ly=pi*(d/2)^4/4;
%Knäckning enligt Euler 2 av stång 1:
Pkr=pi^2*Em*ly/L1^2
%säkerhetsfaktor mot knäckning
Pkr/(-N1)

```

```

clear all
syms a1 a2 a3 a4 a5 a6 a7 a8 P1 P2 P3 P4 P5 P6 P7 P8
%givna storheter
P=10e3;
Em=210e3;
EA=Em*100; L=500;
a1=0; a2=0; a3=0; a4=0; a7=0; a8=0;
P5=P*cos(pi/6); P6=P*sin(pi/6);
%definiera avektor pvektor
avektor = [a1; a2; a3; a4; a5; a6; a7; a8];
Pvektor = [P1; P2; P3; P4; P5; P6; P7; P8];
%elementstyper
%%%Element 1:
L1=L; EA1=EA; alpha1=pi/2; c=cos(alpha1);s=sin(alpha1);
Ke1=EA1/L1*[ c^2 c*s -c^2 -c*s;
c*s s^2 -c*s -s^2;
-c^2 -c*s c^2 c*s;
-c*s -s^2 c*s s^2];
Kmatris1=sym(zeros(8,8));
Kmatris1([1 2 5 6],[1 2 5 6]) = Ke1;
%%%Element 2:
L2=L*sqrt(2); EA2=EA; alpha2=pi/4; c=cos(alpha2);s=sin(alpha2);
Ke2=EA2/L2*[ c^2 c*s -c^2 -c*s;
c*s s^2 -c*s -s^2;
-c^2 -c*s c^2 c*s;
-c*s -s^2 c*s s^2];
Kmatris2=sym(zeros(8,8));
Kmatris2([3 4 5 6],[3 4 5 6]) = Ke2;
%%%Element 3:
L3=L; EA3=EA; alpha3=0; c=cos(alpha3);s=sin(alpha3);
Ke3=EA3/L3*[ c^2 c*s -c^2 -c*s;
c*s s^2 -c*s -s^2;
-c^2 -c*s c^2 c*s;
-c*s -s^2 c*s s^2];
Kmatris3=sym(zeros(8,8));
Kmatris3([7 8 5 6],[7 8 5 6]) = Ke3;
%addera
Ktot=Kmatris1+Kmatris2+Kmatris3;
%Lös de obekanta
Sol = solve(double(Ktot)*avektor==Pvektor,[a5,a6,P1,P2,P3, P4, P7,P8])
%Skriv ut resultat
double(Sol.a5)
double(Sol.a6)
double(Sol.P1)
double(Sol.P2)
double(Sol.P3)
double(Sol.P4)
double(Sol.P7)
double(Sol.P8)

```