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Calculators, formula notes and other subject related material are not allowed.

Each problem gives max 6p. Valid bonus points will be added to the scores.

Breakings: **3**: 15-20p, **4**: 21-27p och **5**: 28p- For GU students **G**:15-24p, **VG**: 25p-

For solutions and gradings information see the course diary in:

<http://www.math.chalmers.se/Math/Grundutb/CTH/tma372/1112/index.html>

1. Prove the following error estimate for the linear interpolation for a function  $f \in C^2(0, 1)$ ,

$$\|\pi_1 f - f\|_{L_\infty(0,1)} \leq \frac{1}{8} \max_{0 \leq \xi \leq 1} |f''(\xi)|.$$

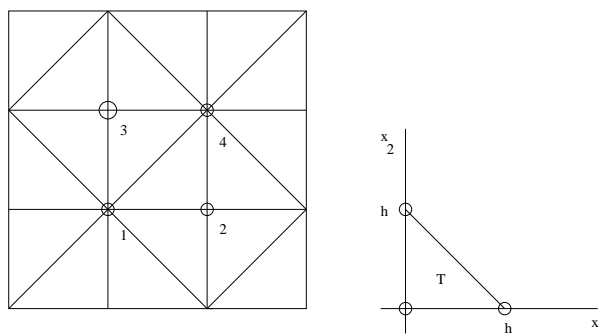
2. Let  $\alpha$  and  $\beta$  be positive constants. Give the piecewise linear finite element approximation procedure, on the uniform mesh, for the problem

$$-u''(x) = 1, \quad 0 < x < 1; \quad u(0) = \alpha, \quad u'(1) = \beta.$$

3. Formulate the  $cG(1)$  method for the boundary value problem

$$-\Delta u + u = f, \quad x \in \Omega; \quad u = 0, \quad x \in \partial\Omega.$$

Write down the matrix form of the resulting equation system using the following uniform mesh:



4. Prove an a priori and an a posteriori error estimate for the  $cG(1)$  finite element method for

$$-u''(x) + xu'(x) + u(x) = f(x), \quad 0 < x < 1, \quad u(0) = u(1) = 0,$$

in the energy norm  $\|v\|_E$  with  $\|v\|_E^2 = \|v\|_{L_2(I)}^2 + \|v'\|_{L_2(I)}^2$ ,  $I := (0,1)$ .

5. Formulate and prove the Lax-Milgram theorem.

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void!

1. By the Lagrange interpolation theorem

$$\|f - \pi_1 f\|_{L_\infty(0,1)} \leq \frac{1}{2}(x-0) \cdot (1-x) \max_{x \in [0,1]} |f''|.$$

Further, the function  $g(x) = x(1-x)$  has minimum when  $g'(x) = 0$ , i.e.  $1 \cdot (1-x) + x \cdot (-1) = 0$ , or for  $x = 1/2$ . Therefore,  $\max_{x \in [0,1]} [x(1-x)] = \max_{x \in [0,1]} g(x) = 1/2(1-1/2) = 1/4$ . Hence

$$\|f - \pi_1 f\|_{L_\infty(0,1)} \leq \frac{1}{8} \|f\|_{L_\infty(0,1)}.$$

2. Multiply the pde by a test function  $v$  with  $v(0) = 0$ , integrate over  $x \in (0,1)$  and use partial integration to get

$$\begin{aligned} (1) \quad & - [u'v]_0^1 + \int_0^1 u'v' dx = \int_0^1 v dx \quad \iff \\ & - u'(1)v(1) + u'(0)v(0) + \int_0^1 u'v' dx = \int_0^1 v dx \quad \iff \\ & - \beta v(1) + \int_0^1 u'v' dx = \int_0^1 v dx. \end{aligned}$$

The continuous variational formulation is now formulated as follows: Find

$$(VF) \quad u \in V := \{w : \int_0^1 (w(x)^2 + w'(x)^2) dx < \infty, \quad w(0) = \alpha\},$$

such that

$$\int_0^1 u'v' dx = \int_0^1 v dx + \beta v(1), \quad \forall v \in V^0,$$

where

$$V^0 := \{v : \int_0^1 (v(x)^2 + v'(x)^2) dx < \infty, \quad v(0) = 0\}.$$

For the discrete version we let  $\mathcal{T}_h$  be a uniform partition:  $0 = x_0 < x_1 < \dots < x_{M+1}$  of  $[0,1]$  into the subintervals  $I_n = [x_{n-1}, x_n]$ ,  $n = 1, \dots, M+1$ . Here, we have  $M$  interior nodes:  $x_1, \dots, x_M$ , two boundary points:  $x_0 = 0$  and  $x_{M+1} = 1$  and hence  $M+1$  intervals.

The finite element method (discrete variational formulation) is now formulated as follows: Find

$$(FEM) \quad U \in V_h := \{w_h : w_h \text{ is piecewise linear, continuous on } \mathcal{T}_h, w_h(0) = \alpha\},$$

such that

$$(2) \quad \int_0^1 U'v_h' dx = \int_0^1 v_h dx + \beta v_h(1), \quad \forall v_h \in V_h^0,$$

where

$$V_h^0 := \{v_h : v_h \text{ is piecewise linear, continuous on } \mathcal{T}_h, v_h(0) = 0\}.$$

Using the basis functions  $\varphi_j$ ,  $j = 0, \dots, M+1$ , where  $\varphi_1, \dots, \varphi_M$  are the usual *hat-functions* whereas  $\varphi_0$  and  $\varphi_{M+1}$  are *semi-hat-functions* viz;

$$(3) \quad \varphi_j(x) = \begin{cases} 0, & x \notin [x_{j-1}, x_j] \\ \frac{x-x_{j-1}}{h} & x_{j-1} \leq x \leq x_j \\ \frac{x_{j+1}-x}{h} & x_j \leq x \leq x_{j+1} \end{cases}, \quad j = 1, \dots, M.$$

and

$$\varphi_0(x) = \begin{cases} \frac{x_1-x}{h} & 0 \leq x \leq x_1 \\ 0, & x_1 \leq x \leq 1 \end{cases}, \quad \varphi_{M+1}(x) = \begin{cases} \frac{x-x_M}{h} & x_M \leq x \leq x_{M+1} \\ 0, & 0 \leq x \leq x_M. \end{cases}$$

In this way we may write

$$V_h = \alpha\varphi_0 \oplus [\varphi_1, \dots, \varphi_{M+1}], \quad V_h^0 = [\varphi_1, \dots, \varphi_{M+1}].$$

Thus every  $U \in V_h$  can be written as  $U = \alpha\varphi_0 + v_h$  where  $v_h \in V_h^0$ , i.e.,

$$U = \alpha\varphi_0 + \xi_1\varphi_1 + \dots + \xi_{M+1}\varphi_{M+1} = \alpha\varphi_0 + \sum_{i=1}^{M+1} \xi_i\varphi_i \equiv \alpha\varphi_0 + \tilde{U},$$

where  $\tilde{U} \in V_h^0$ , and hence the problem (2) can equivalently be formulated as to find  $\xi_1, \dots, \xi_{M+1}$  such that

$$\int_0^1 \left( \alpha\varphi_0' + \sum_{i=1}^{M+1} \xi_i\varphi_i' \right) \varphi_j' dx = \int_0^1 \varphi_j dx + \beta\varphi_j(1), \quad j = 1, \dots, M+1,$$

which can be written as

$$\sum_{i=1}^{M+1} \left( \int_0^1 \varphi_j' \varphi_i' dx \right) \xi_i = - \int_0^1 \varphi_0' \varphi_j' dx + \int_0^1 \varphi_j dx + \beta\varphi_j(1), \quad j = 1, \dots, M+1,$$

or equivalently  $A\xi = b$  where  $A = (a_{ij})$  is the tridiagonal matrix with entries

$$a_{ii} = 2, \quad a_{i,i+1} = a_{i+1,i} = -1, \quad i = 1, \dots, M, \quad \text{and} \quad a_{M+1,M+1} = 1,$$

i.e.,

$$A = \frac{1}{h} \begin{bmatrix} 2 & -1 & 0 & 0 & \dots & 0 & 0 \\ -1 & 2 & -1 & 0 & \dots & 0 & 0 \\ \dots & & & & & & \\ \dots & & & & & & \\ \dots & & & & & & \\ 0 & 0 & \dots & 0 & -1 & 2 & -1 \\ 0 & 0 & \dots & 0 & 0 & -1 & 1 \end{bmatrix},$$

and the unknown  $\xi$  and the data  $b$  are given by

$$\xi = \begin{bmatrix} \xi_1 \\ \xi_2 \\ \vdots \\ \xi_M \\ \xi_{M+1} \end{bmatrix}, \quad b = \begin{bmatrix} \int_0^1 \varphi_1 dx - \alpha \int_0^1 \varphi_0' \varphi_1' dx \\ \int_0^1 \varphi_2 dx \\ \vdots \\ \int_0^1 \varphi_M dx \\ \int_0^1 \varphi_{M+1} dx + \beta\varphi_{M+1}(1) \end{bmatrix} = \begin{bmatrix} h + \frac{1}{h}\alpha \\ h \\ \vdots \\ h \\ \frac{h}{2} + \beta \end{bmatrix}.$$

**3.** Let  $V_h$  be the usual finite element space consisting of continuous piecewise linear functions satisfying the boundary condition  $v = 0$  on  $\partial\Omega$ . The  $cG(1)$  method is: Find  $U \in V_h$  such that

$$(\nabla U, \nabla v) + (U, v) = (f, v) \quad \forall v \in V_h$$

Making the ‘‘Ansatz’’  $U(x) = \sum_{i=1}^4 \xi_i \varphi_i(x)$ , where  $\varphi_i$  are the standard basis functions, we obtain the system of equations

$$\sum_{i=1}^4 \xi_i \left( \int_{\Omega} \nabla \varphi_i \cdot \nabla \varphi_j dx + \int_{\Omega} \varphi_i \varphi_j dx \right) = \int_{\Omega} f \varphi_j dx, \quad j = 1, \dots, 4,$$

or, in matrix form,

$$(S + M)\xi = F,$$

where  $S_{ij} = (\nabla \varphi_i, \nabla \varphi_j)$  is the stiffness matrix,  $M_{ij} = (\varphi_i, \varphi_j)$  is the mass matrix, and  $F_j = (f, \varphi_j)$  is the load vector.

We first compute the mass and stiffness matrix for the reference triangle  $T$ . The local basis functions are

$$\begin{aligned}
\phi_1(x_1, x_2) &= 1 - \frac{x_1}{h} - \frac{x_2}{h}, & \nabla\phi_1(x_1, x_2) &= -\frac{1}{h} \begin{bmatrix} 1 \\ 1 \end{bmatrix}, \\
\phi_2(x_1, x_2) &= \frac{x_1}{h}, & \nabla\phi_2(x_1, x_2) &= \frac{1}{h} \begin{bmatrix} 1 \\ 0 \end{bmatrix}, \\
\phi_3(x_1, x_2) &= \frac{x_2}{h}, & \nabla\phi_3(x_1, x_2) &= \frac{1}{h} \begin{bmatrix} 0 \\ 1 \end{bmatrix}.
\end{aligned}$$

Hence, with  $|T| = \int_T dz = h^2/2$ ,

$$\begin{aligned}
m_{11} &= (\phi_1, \phi_1) = \int_T \phi_1^2 dx = h^2 \int_0^1 \int_0^{1-x_2} (1-x_1-x_2)^2 dx_1 dx_2 = \frac{h^2}{12}, \\
s_{11} &= (\nabla\phi_1, \nabla\phi_1) = \int_T |\nabla\phi_1|^2 dx = \frac{2}{h^2} |T| = 1.
\end{aligned}$$

Alternatively, we can use the midpoint rule, which is exact for polynomials of degree 2 (precision 3):

$$m_{11} = (\phi_1, \phi_1) = \int_T \phi_1^2 dx = \frac{|T|}{3} \sum_{j=1}^3 \phi_1(\hat{x}_j)^2 = \frac{h^2}{6} \left(0 + \frac{1}{4} + \frac{1}{4}\right) = \frac{h^2}{12},$$

where  $\hat{x}_j$  are the midpoints of the edges. Similarly we can compute the other elements and obtain

$$m = \frac{h^2}{24} \begin{bmatrix} 2 & 1 & 1 \\ 1 & 2 & 1 \\ 1 & 1 & 2 \end{bmatrix}, \quad s = \frac{1}{2} \begin{bmatrix} 2 & -1 & -1 \\ -1 & 1 & 0 \\ -1 & 0 & 1 \end{bmatrix}.$$

We can now assemble the global matrices  $M$  and  $S$  from the local ones  $m$  and  $s$ :

$$\begin{aligned}
M_{11} &= M_{44} = 8m_{22} = \frac{8}{12}h^2, & S_{11} &= S_{44} = 8s_{22} = 4, \\
M_{12} &= M_{13} = M_{24} = M_{34} = 2m_{12} = \frac{1}{12}h^2, & S_{12} &= S_{13} = S_{24} = S_{34} = 2s_{12} = -1, \\
M_{14} &= 2m_{23} = \frac{1}{12}h^2, & S_{14} &= 2s_{23} = 0, \\
M_{22} &= M_{33} = 4m_{11} = \frac{4}{12}h^2, & S_{22} &= S_{33} = 4s_{11} = 4, \\
M_{23} &= 0, & S_{23} &= 0.
\end{aligned}$$

The remaining matrix elements are obtained by symmetry  $M_{ij} = M_{ji}$ ,  $S_{ij} = S_{ji}$ . Hence,

$$M = \frac{h^2}{12} \begin{bmatrix} 8 & 1 & 1 & 1 \\ 1 & 4 & 0 & 1 \\ 1 & 0 & 4 & 1 \\ 1 & 1 & 1 & 8 \end{bmatrix}, \quad S = \begin{bmatrix} 4 & -1 & -1 & 0 \\ -1 & 4 & 0 & -1 \\ -1 & 0 & 4 & -1 \\ 0 & -1 & -1 & 4 \end{bmatrix}.$$

**4.** We multiply the differential equation by a test function  $v \in H_0^1 = \{v : \|v\| + \|v'\| < \infty, v(0) = 0\}$  and integrate over  $I$ . Using partial integration and the boundary conditions we get the following *variational problem*: Find  $u \in H_0^1(I)$  such that

$$(4) \quad \int_I (u'v' + xu'v + uv) = \int_I fv, \quad \forall v \in H_0^1(I).$$

A *Finite Element Method* with  $cG(1)$  reads as follows: Find  $U \in V_h^0$  such that

$$(5) \quad \int_I (U'v' + xU'v + Uv) = \int_I fv, \quad \forall v \in V_h^0 \subset H_0^1(I),$$

where

$$V_h^0 = \{v : v \text{ is piecewise linear and continuous in a partition of } I, v(0) = v(1) = 0\}.$$

Now let  $e = u - U$ , then (4)-(5) gives that

$$(6) \quad \int_I (e'v' + xe'v + ev) = 0, \quad \forall v \in V_h^0, \quad (\text{Galerkin Ortogonalitet}).$$

We note that using  $e(0) = e(1) = 0$ , we get

$$(7) \quad \int_I xe'e = \frac{1}{2} \int_I x \frac{d}{dx}(e^2) = \frac{1}{2}(xe^2)|_0^1 - \frac{1}{2} \int_I e^2 = -\frac{1}{2} \int_I e^2,$$

Further, using Poincare inequality we have

$$\|e\|^2 \leq \|e'\|^2.$$

*A priori error estimate:* We use (6) and (7) to get

$$\begin{aligned} \|e'\|_{L_2(I)}^2 + \frac{1}{2}\|e\|_{L_2}^2 &= \int_I (e'e' + \frac{1}{2}ee) = \int_I (e'e' + xe'e + ee) \\ &= \int_I (e'(u-U)' + xe'(u-U) + e(u-U)) = \{v = U - \pi_h u \text{ i(6)}\} \\ &= \int_I (e'(u - \pi_h u)' + xe'(u - \pi_h u) + e(u - \pi_h u)) \\ &\leq \|(u - \pi_h u)'\| \|e'\| + \|u - \pi_h u\| \|e'\| + \|u - \pi_h u\| \|e\| \\ &\leq \{ \|(u - \pi_h u)'\| + \sqrt{2}\|u - \pi_h u\| \} \|e\|_{H^1} \\ &\leq C_i \{ \|hu''\| + \sqrt{2}\|h^2u''\| \} \|e\|_{H^1}. \end{aligned}$$

this gives that

$$\|e\|_{H^1} \leq 2C_i \{ \|hu''\| + \sqrt{2}\|h^2u''\| \}.$$

which is the a priori error estimate.

*A posteriori error estimate:*

$$\begin{aligned} \|e'\|_{L_2(I)}^2 + \frac{1}{2}\|e\|_{L_2}^2 &= \int_I (e'e' + \frac{1}{2}ee) = \int_I (e'e' + xe'e + ee) \\ &= \int_I ((u-U)'e' + x(u-U)'e + (u-U)e) = \{v = e \text{ in (4)}\} \\ (8) \quad &= \int_I fe - \int_I (U'e' + xU'e + Ue) = \{v = \pi_h e \text{ in (6)}\} \\ &= \int_I f(e - \pi_h e) - \int_I (U'(e - \pi_h e)' + xU'(e - \pi_h e) + U(e - \pi_h e)) \\ &= \{P.I. \text{ on each subinterval}\} = \int_I \mathcal{R}(U)(e - \pi_h e), \end{aligned}$$

where  $\mathcal{R}(U) := f + U'' - xU' - U = f - xU' - U$ , (for approximation with piecewise linears,  $U \equiv 0$ , on each subinterval). Thus (5) implies that

$$\|e'\|_{L_2(I)}^2 + \frac{1}{2}\|e\|_{L_2}^2 \leq \|h\mathcal{R}(U)\| \|h^{-1}(e - \pi_h e)\| \leq C_i \|h\mathcal{R}(U)\| \|e'\| \leq \frac{1}{2}C_i^2 \|h\mathcal{R}(U)\|^2 + \frac{1}{2}\|e'\|_{L_2(I)}^2,$$

where  $C_i$  is an interpolation constant, and hence we have with  $\|\cdot\| = \|\cdot\|_{L_2(I)}$  that

$$\|e\|_{H^1} \leq C_i \|h\mathcal{R}(U)\|.$$

**5.** See the Book and/or Lecture Notes.

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