

TMA372/MMG800: Partial Differential Equations, 2011–06–04; kl 8.30-13.30.

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Calculators, formula notes and other subject related material are not allowed.

Each problem gives max 5p. Valid bonus points will be added to the scores.

Breakings: **3:** 15-20p, **4:** 21-27p och **5:** 28p- For GU students **G:**15-27p, **VG:** 28p-

For solutions and gradings information see the course diary in:

<http://www.math.chalmers.se/Math/Grundutb/CTH/tma372/1011/index.html>

1. Let $\pi_1 f$ be the linear interpolant of a twice continuously differentiable function f on the interval (a, b) . Prove that

$$\|f - \pi_1 f\|_{L^\infty(a,b)} \leq (b - a)^2 \|f''\|_{L^\infty(a,b)}.$$

2. Prove an a priori and an a posteriori error estimate for the cG(1) finite element method for

$$-u''(x) + u'(x) = f, \quad 0 < x < 1; \quad u(0) = u(1) = 0.$$

3. Derive the cG(1)-cG(1), Crank-Nicolson approximation, for the initial boundary value problem

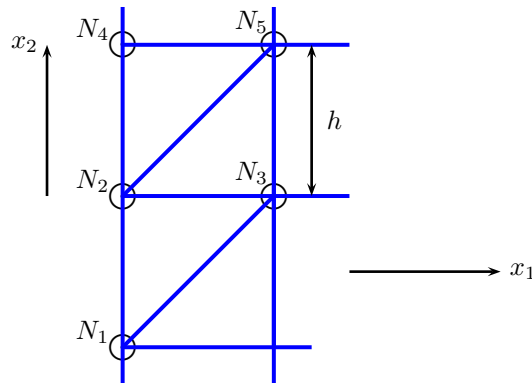
$$\begin{cases} \dot{u} - u'' = f, & 0 < x < 1, & t > 0, \\ u'(0, t) = u'(1, t) = 0, & u(x, 0) = 0, & x \in [0, 1], t > 0, \end{cases} \quad (1)$$

4. Show that the cG(1)-cG(1) solution for wave equation in 1d satisfies the conservation of energy:

$$\|U'_n\| + \|\dot{U}_n\| = \|U'_{n-1}\| + \|\dot{U}_{n-1}\|. \quad (2)$$

5. Let Ω be the domain in the figure below, with the given triangulation and nodes $N_i, i = 1, \dots, 5$. Let U be the cG(1) solution to the problem

$$-\Delta u = 1, \quad \text{in } \Omega \subset \mathbf{R}^2, \quad \text{with} \quad -\mathbf{n} \cdot \nabla u = 0, \quad \text{on } \partial\Omega. \quad (3)$$



a) Given the test function φ_2 at node N_2 , find the relation between $U_1, U_2, U_3, U_4,$ and U_5 .

b) Derive the corresponding relation when the equation is replaced by $-\Delta u + (1, 0) \cdot \nabla u = 1$.

6. (a) p and q are positive constants. Verify in details that the coefficient matrix for the cG(1) method for

$$\begin{cases} -u''(x) + pu(x) = f(x), & x \in (0, 1), \\ u'(0) = u'(1) = q, \end{cases}$$

is symmetric, positive definite and tridiagonal.

(b) For which values for the parameter p is the coefficient matrix diagonal?

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void!

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Lösningar/Solutions.

1. See Lecture Notes.

2. We multiply the differential equation by a test function $v \in H_0^1(I)$, $I = (0, 1)$ and integrate over I . Using partial integration and the boundary conditions we get the following *variational problem*: Find $u \in H_0^1(I)$ such that

$$\int_I (u'v' + u'v) = \int_I f v, \quad \forall v \in H_0^1(I). \quad (4)$$

A *Finite Element Method* with $cG(1)$ reads as follows: Find $U \in V_h^0$ such that

$$\int_I (U'v' + U'v) = \int_I f v, \quad \forall v \in V_h^0 \subset H_0^1(I), \quad (5)$$

where

$$V_h^0 = \{v : v \text{ is piecewise linear and continuous in a partition of } I, v(0) = v(1) = 0\}.$$

Now let $e = u - U$, then (1)-(2) gives that

$$\int_I (e'v' + e'v) = 0, \quad \forall v \in V_h^0. \quad (6)$$

We note that using $e(0) = e(1) = 0$, we get

$$\int_I e'e = \int_I \frac{1}{2} \frac{d}{dx} (e^2) = \frac{1}{2} (e^2)|_0^1 = 0. \quad (7)$$

Further, using Poincare inequality we have

$$\|e\|^2 \leq \|e'\|^2.$$

A priori error estimate: We use Poincare inequality and (7) to get

$$\begin{aligned} \|e\|_{H^1}^2 &= \int_I (e'e' + ee) \leq 2 \int_I e'e' = 2 \int_I (e'e' + e'e) = 2 \int_I (e'(u-U)' + e'(u-U)) \\ &= 2 \int_I (e'(u - \pi_h u)' + e'(u - \pi_h u)) + 2 \int_I (e'(\pi_h u - U)' + e'(\pi_h u - U)) \\ &= \{v = U - \pi_h u \text{ in (6)}\} = 2 \int_I (e'(u - \pi_h u)' + e'(u - \pi_h u)) \\ &\leq 2\|(u - \pi_h u)'\| \|e'\| + 2\|u - \pi_h u\| \|e'\| \\ &\leq 2C_i \{\|hu''\| + \|h^2 u''\|\} \|e\|_{H^1}, \end{aligned}$$

this gives that

$$\|e\|_{H^1} \leq C_i \{\|hu''\| + \|h^2 u''\|\},$$

which is the a priori error estimate.

A posteriori error estimate:

$$\begin{aligned}
\|e\|_{H^1}^2 &= \int_I (e'e' + ee) \leq 2 \int_I e'e' = 2 \int_I (e'e' + e'e) \\
&= 2 \int_I ((u-U)'e' + (u-U)'e) = \{v = e \text{ in (4)}\} \\
&= 2 \int_I fe - \int_I (U'e' + U'e) = \{v = \pi_h e \text{ in (5)}\} \\
&= \int_I f(e - \pi_h e) - \int_I (U'(e - \pi_h e)' + U'(e - \pi_h e)) \\
&= \{P.I. \text{ on each subinterval}\} = \int_I \mathcal{R}(U)(e - \pi_h e),
\end{aligned} \tag{8}$$

where $\mathcal{R}(U) := f + U'' - U' = f - U'$, (for approximation with piecewise linears, $U \equiv 0$, on each subinterval). Thus (5) implies that

$$\begin{aligned}
\|e\|_{H^1}^2 &\leq \|h\mathcal{R}(U)\| \|h^{-1}(e - \pi_h e)\| \\
&\leq C_i \|h\mathcal{R}(U)\| \|e'\| \leq C_i \|h\mathcal{R}(U)\| \|e\|_{H^1},
\end{aligned}$$

where C_i is an interpolation constant, and hence we have with $\|\cdot\| = \|\cdot\|_{L_2(I)}$ that

$$\|e\|_{H^1} \leq C_i \|h\mathcal{R}(U)\|.$$

3. Make the cG(1)-cG(1) ansatz

$$U(x, t) = U_{n-1}(x)\psi_{n-1}(t) + U_n(x)\psi_n(t), \quad \text{with } U_n(x) = \sum_{j=1}^M U_{n,j}\varphi_j(x),$$

in the variational formulation

$$\int_{I_n} \int_0^1 u'v' = \int_{I_n} \int_0^1 f v, \quad I_n = (t_{n-1}, t_n).$$

Recall that $v = \varphi_j(x)$, $j = 1, \dots, M$ and

$$\psi_{n-1}(t) = \frac{t_n - t}{t_n - t_{n-1}}, \quad \psi_n(t) = \frac{t - t_{n-1}}{t_n - t_{n-1}}.$$

For a uniform tile partition with $k := t_n - t_{n-1}$, this yields the equation system

$$(M + \frac{k}{2}S)U_n = (M - \frac{k}{2}S)U_{n-1} + k\mathbf{b}_n.$$

Here U_n is the node-vale vector with entries $U_{n,j}$, M is the mass-matrix with elements $\int_0^1 \varphi_i(x)\varphi_j(x)$, S is the stiffness-matrix with elements $\int_0^1 \varphi_i'(x)\varphi_j'(x)$, and \mathbf{b}_n is the load vector with elements $\frac{1}{k} \int_{I_n} \int_0^1 f \varphi_i(x)$. The corresponding dG0 (\approx implicit Euler) time-stepping yields

$$(M + kS)U_n = MU_{n-1} + k\mathbf{b}_n.$$

4. Following the lecture notes, we may write the wave equation

$$\begin{cases} \ddot{u} - u'' = 0, & 0 < x < 1, & t > 0, \\ u(0, t) = 0, & u'(0, t) = g(t), t > 0, & \\ u(x, 0) = u_0(x), & \dot{u}(x, 0) = v_0(x), & 0 < x < 1, \end{cases}$$

in a system viz,

$$\begin{cases} \dot{u} = v, & t > 0, \\ \dot{v} = u'' & t > 0, \end{cases}$$

for which the cG(1) method yields the matrix system

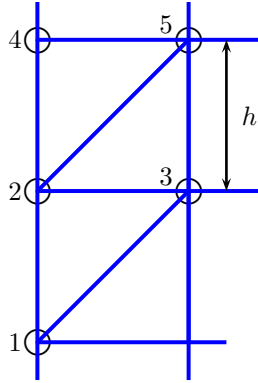
$$\begin{cases} MU_n - \frac{k}{2}MV_n = MU_{n-1} + \frac{k}{2}MV_{n-1} \\ \frac{k}{2}SU_n + MV_n = -\frac{k}{2}SU_{n-1} + MV_{n-1} + g_n, \end{cases}$$

with M and S being the mass and stiffness matrices, respectively. Let $g(t) \equiv 0$, and multiply the first equation by $(U_n + U_{n-1})^t S M^{-1}$ and the second equation by $(V_n + V_{n-1})^t$. Adding up and using the identities as $W_n^t S W_n = \|W_n'\|^2$, and $P^t A Q = Q^t A P$, for $A = S, M$ yields the desired result.

5. a) With U expressed in terms of the basis functions φ_j , $j = 1, 2, 3, 4, 5$ and with the test function $v = \varphi_2$ in the variational formulation we obtain the relation

$$-\frac{1}{2}U_1 + 2U_2 - U_3 - \frac{1}{2}U_4 = \frac{1}{2}h^2.$$

b) If we change the equation to $-\Delta u + (1, 0) \cdot \nabla u = 1$ the relation between the nodal values



becomes:

$$-\frac{1}{2}U_1 + 2U_2 - U_3 - \frac{1}{2}U_4 - \frac{h}{3}U_2 + \frac{h}{3}U_3 - \frac{h}{6}U_4 + \frac{h}{6}U_5 = \frac{1}{2}h^2.$$

Finally if, for instance, for $-\nabla \cdot a \nabla u = f$ with $a = 1$ for $x < 0$ and $a = 2$ for $x_2 > 0$, the corresponding relation is:

$$-\frac{1}{2}U_1 + 3U_2 - \frac{3}{2}U_3 - U_4 = \frac{1}{2}h^2.$$

You may work out the details in such a model!

6. Let V and V_h be the spaces of continuous and discrete solutions, respectively. The variational formulation is: Find $u \in V$ such that

$$-\int_0^1 (u''(x) - pu(x))v(x) dx = \int_0^1 f(x)v(x) dx, \quad \forall v \in V.$$

Integrating by parts and using the fact that $u'(0) = u'(1) = q$ we get

$$-\int_0^1 u'v' dx + p \int_0^1 uv dx = \int_0^1 f(x)v(x) dx + q(v(1) - v(0)), \quad \forall v \in V.$$

The corresponding $cG(1)$ method reads: Find $U \in V_h$ such that

$$-\int_0^1 U'v' dx + p \int_0^1 Uv dx = \int_0^1 f(x)v(x) dx + q(v(1) - v(0)), \quad \forall v \in V_h.$$

If $U = \sum_{j=1}^M \xi_j \varphi_j(x)$, then we get the following system of equations:

$$\int_0^1 \sum_{j=1}^M \xi_j \varphi_j' \varphi_i' dx + p \int_0^1 \sum_{j=1}^M \xi_j \varphi_j \varphi_i dx = \int_0^1 f(x) \varphi_i dx + q(\varphi_i(1) - \varphi_i(0)), \quad i = 1, \dots, M.$$

Or equivalently

$$\sum_{j=1}^M \xi_j \int_0^1 (\varphi_j' \varphi_i' + p \varphi_j \varphi_i) dx = \int_0^1 f(x) \varphi_i dx + q(\varphi_i(1) - \varphi_i(0)), \quad i = 1, \dots, M.$$

That is we have the system $A\xi = b$ with

$$\begin{cases} a_{ij} &= \int_0^1 (\varphi'_j \varphi'_i + p \varphi_j \varphi_i) dx = \tilde{a}_{ij} + p \int_0^1 \varphi_j \varphi_i dx, & \tilde{a}_{ij} = \int_0^1 \varphi'_j \varphi'_i dx \\ b_i &= \int_0^1 f(x) \varphi_i dx + q(\varphi_i(1) - \varphi_i(0)). \end{cases}$$

The stiffness matrix is obviously *symmetric*, since $a_{ij} = a_{ji}$. To see if A is positive definite, we form for any vector $v \in \mathbb{R}^M$

$$\begin{aligned} v^t A v &= \sum_{i=1}^M v_i \left(\sum_{j=1}^M a_{ij} v_j \right) = \sum_{i=1}^M v_i \left[\sum_{j=1}^M v_j \int_0^1 (\varphi'_j \varphi'_i + p \varphi_j \varphi_i) dx \right] \\ &= \int_0^1 \sum_{i=1}^M v_i \left[\sum_{j=1}^M v_j (\varphi'_j \varphi'_i + p \varphi_j \varphi_i) dx \right] \\ &= \int_0^1 \sum_{i=1}^M v_i \left(\sum_{j=1}^M v_j \varphi'_j \varphi'_i \right) dx + \int_0^1 \sum_{i=1}^M v_i \left(\sum_{j=1}^M v_j p \varphi_j \varphi_i \right) dx \\ &= \int_0^1 \sum_{i=1}^M v_i \varphi'_i \left(\sum_{j=1}^M v_j \varphi'_j \right) dx + p \int_0^1 \sum_{i=1}^M v_i \varphi_i \left(\sum_{j=1}^M v_j \varphi_j \right) dx \\ &= \int_0^1 \left(\sum_{i=1}^M v_i \varphi'_i \right)^2 dx + p \int_0^1 \left(\sum_{i=1}^M v_i \varphi_i \right)^2 dx. \end{aligned} \tag{9}$$

Thus $v^t A v \geq 0$ and $v^t A v = 0 \iff v = 0$, since $p \geq 0$. Hence A is positive definite.

To see if A is tridiagonal we compute the elements a_{ij} :

$$a_{ij} = 0, \quad \text{if } |i - j| > 1. \tag{10}$$

Since the support for the basis functions overlap only for adjacent nodes.

$$\begin{aligned} a_{ii} &= \tilde{a}_{ii} + p \int_0^1 \varphi_i^2 dx \\ &= \frac{1}{h_i} + \frac{1}{h_{i+1}} + p \int_{x_{i-1}}^{x_i} \left(\frac{x - x_{i-1}}{h_i} \right)^2 dx + p \int_{x_i}^{x_{i+1}} \left(\frac{x - x_{i+1}}{-h_{i+1}} \right)^2 dx \\ &= \frac{1}{h_i} + \frac{1}{h_{i+1}} + \frac{p}{3} (h_i + h_{i+1}). \end{aligned} \tag{11}$$

$$\begin{aligned} a_{i,i+1} &= \tilde{a}_{i,i+1} + p \int_0^1 \varphi_i \varphi_{i+1} dx \\ &= -\frac{1}{h_{i+1}} + p \int_{x_i}^{x_{i+1}} \frac{x - x_{i+1}}{-h_{i+1}} \cdot \frac{x - x_i}{h_{i+1}} dx \\ &= -\frac{1}{h_{i+1}} - \frac{p}{h_{i+1}^2} \left[(x - x_{i+1}) \frac{(x - x_i)^2}{2} \right]_{x_i}^{x_{i+1}} + \frac{p}{h_{i+1}^2} \int_{x_i}^{x_{i+1}} \frac{(x - x_i)^2}{2} dx \\ &= -\frac{1}{h_{i+1}} + \frac{p}{6} h_{i+1}. \end{aligned} \tag{12}$$

Obviously (10)-(12) means that A is tridiagonal.

Since we may choose $p = \frac{6}{h_{i+1}^2}$, it is possible that $a_{i,i+1} = 0$. A may even be diagonal (for a uniform triangulation). In general, though, A is *tridiagonal*.

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